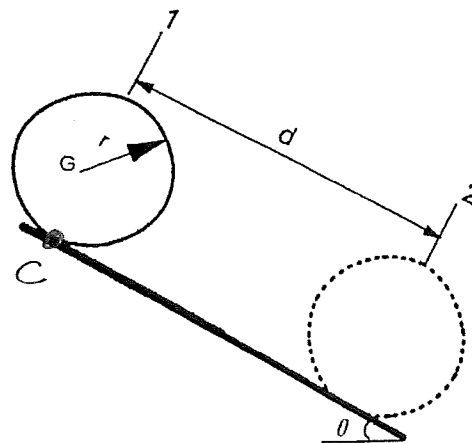
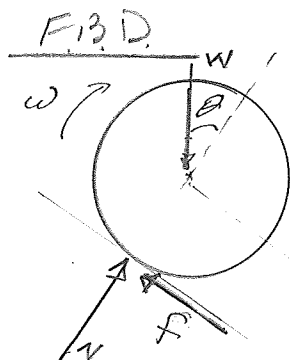


A disk of mass m starts from rest and rolls without slipping on an inclined surface. Find: a) angular velocity, b) velocity of the center of gravity



$$T_1 + \sum U_{12} = T_2$$

Therefore!

$$U_{12} = mgsin\theta d$$

$$T_2 = \frac{1}{2} m v_G^2 + \frac{1}{2} I_G \omega^2$$

Substituting

$$T_2 = \frac{1}{2} m [r\omega]^2 + \frac{1}{2} I_G \omega^2$$

$$T_2 = \frac{1}{2} \omega^2 [I_G + mr^2] = \frac{1}{2} \omega^2 [I_C]$$

$$\therefore T_2 = \frac{1}{2} I_C \omega^2$$

$$\text{Thus: } 0 + mgsin\theta d = \frac{1}{2} I_C \omega^2$$

$$mgsin\theta d = \frac{1}{2} \cdot \frac{3}{2} m R^2 \omega^2$$

Solving

$$\omega = \sqrt{\frac{4gsin\theta d}{3R^2}}$$

Note: $\vec{O}f$ and N DO NO WORK

Since at each instant they act on a point C which has zero velocity [PT. of contact is the I.C.]

(2) ONLY force doing work is weight

(3) From the fact that the disk rolls w/o slip

$$v_G = r\omega \text{ (No slip)}$$

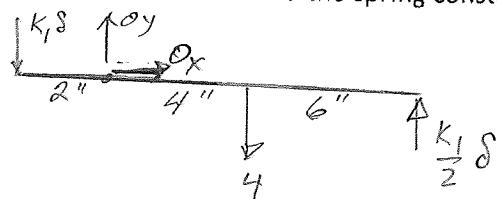
(4) $I_G + mr^2 = I_C$ } PARALLEL-AXIS THEOREM.
 $C = I.C. \therefore$ zero velocity

(5) For a disk I about point of contact is:

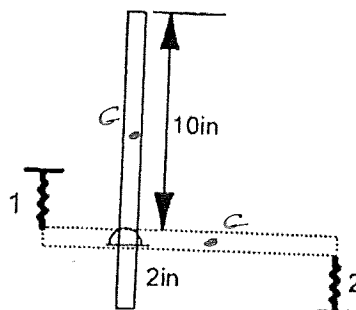
$$I_C = \frac{3}{2} m R^2$$

$$v_G = r\omega = \sqrt{\frac{4}{3} g d sin\theta}$$

The angular velocity of the 4-lb homogeneous bar is 8 rad/s clockwise in the vertical position. After the bar rotates 90° clockwise, it strikes the two springs and continues to rotate until spring 1 is compressed 0.20 in. The spring constant of spring 1 is twice that of spring 2. The springs are unstressed when the bar first strikes them. Find the spring constant of spring 1.



Note:
 $g = 386 \text{ in/s}^2$



$$T_1 + \sum U_{12} = T_2$$

$$4(4 + 0.4) - \int_0^{0.2} K_1 s ds - \int_0^1 \frac{K_1}{2} s ds = \frac{1}{2} \left[\frac{1}{12} \left(\frac{4}{386} \right) (12)^2 + \frac{4}{386} (4)^2 \right] [0^2 - (8)^2]$$

$$17.6 - K_1 \frac{s^2}{2} \Big|_0^{0.2} - \frac{K_1}{2} \frac{s^2}{2} \Big|_0^1 = -18.573$$

$$17.6 - 0.02 K_1 - 0.25 K_1 = -18.573$$

$$K_1 = 133.97 \approx \underline{\underline{134 \text{ lb/in}}}$$